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%=====
%  PROGRAM temperature_steady.m
%=====

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clear
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%-----
%  LOAD DATA
%-----

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load MESHo    -ASCII
load NODES    -ASCII
load NP       -ASCII
load NWLD     -ASCII
load PSI      -ASCII

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%load vCoef -ASCII
vCoef = 2;
PSI = PSI*vCoef;

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NUMNP = MESHo(1);
NUMEL = MESHo(2);
NNPE  = MESHo(3);

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for I=1:NUMNP;
    XORD(I)=NODES(I,1);
    YORD(I)=NODES(I,2);
    NPcode(I)=NODES(I,3);
end

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% -----
%  Determine bandwidth and
%  diagonal column for
%  nonsymmetric storage
% -----

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IB    = NWLD(NUMNP+1);
IDIAG=IB;
IB    = 2*IB-1;

```

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% -----
%  General Initialization
% -----

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PI=4.0*atan(1.0);
if NNPE == 3
    NSPE=3;
    NNPS=2;
elseif NNPE == 6
    NSPE=3;
    NNPS=3;
elseif NNPE == 4
    NSPE=4;
    NNPS=2;
elseif NNPE == 8
    NSPE=4;
    NNPS=3;
end

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for I=1:NUMNP;
    Q(I)=0;
    QS(I)=0;

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    HS(I)=0;
    PHI(I)=0;
    PHIA(I)=0;
    NPBC(I)=0;
end

for I=1:NUMNP
    for J=1:IB
        SK(I,J)=0;
    end
end

% -----
% Ask User for type of analysis desired
% -----
%     disp(' ')
%     disp('ENTER:')
%     disp('-----')
%     disp('0 for 2D rectangular analysis')
%     disp('1 for axi-symmetric analysis about x-axis')
%     disp('2 for axi-symmetric analysis about y-axis')
%     disp('-----')
%     IRZ = input(' < ');
%
%     if IRZ < 0 | IRZ > 2
%         disp('-----')
%         disp('ERROR IN INPUT ')
%         disp('IRZ has been set to 0')
%         disp('-----')
%         IRZ = 0;
%     end

IRZ = 0;

% -----
% Get shape function quadrature data
% -----
[ SF,WT,NUMQPT,NPSIDE] = SFquad(NNPE);

% -----
% Include user written initialization
% -----
temperature_INITIAL

% -----
% Place Q in RHS, compact storage
% -----
for I=1:NUMNP
    RHS(NWLD(I))=Q(I);
end

% -----
% Create element matrices
% -----
for I=1:NUMEL;
    LMENT=I;
    for J=1:NNPE;

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    QE(J)=0.0;
    for K=1:NNPE;
        S(J,K)=0;
    end
end

```

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% -----
% Begin volume quadrature for each element
% -----

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JEND=NUMQPT(1);
for J=1:JEND;
    XJ=0;
    YJ=0;
    RJAC(1,1)=0;
    RJAC(1,2)=0;
    RJAC(2,1)=0;
    RJAC(2,2)=0;

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% -----
% Determine coordinate and Jacobian
% -----

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for K=1:NNPE;
    NPK=NP(I,K);
    XJ=XJ+SF(1,K,J)*XORD(NPK);
    YJ=YJ+SF(1,K,J)*YORD(NPK);
    RJAC(1,1)=RJAC(1,1)+SF(2,K,J)*XORD(NPK);
    RJAC(1,2)=RJAC(1,2)+SF(3,K,J)*XORD(NPK);
    RJAC(2,1)=RJAC(2,1)+SF(2,K,J)*YORD(NPK);
    RJAC(2,2)=RJAC(2,2)+SF(3,K,J)*YORD(NPK);
end

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DETJ=RJAC(1,1)*RJAC(2,2)...
    -RJAC(2,1)*RJAC(1,2);
if DETJ <= 0
    fprintf(1, '\n-----')
    fprintf(1, '\n Error in steady.m      ')
    fprintf(1, '\n DETJ =%7e', DETJ        )
    fprintf(1, '\n must be > 0.0'         )
    fprintf(1, '\n-----\n')
    error
end

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% -----
% Determine inverse of Jacobian
% -----

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RJACI(1,1)=+RJAC(2,2)/DETJ;
RJACI(1,2)=-RJAC(1,2)/DETJ;
RJACI(2,1)=-RJAC(2,1)/DETJ;
RJACI(2,2)=+RJAC(1,1)/DETJ;

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% -----
% Determine derivative of shape functions in X-Y plane
% -----

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for K=1:NNPE;
    DNDX(K)=RJACI(1,1)*SF(2,K,J)+RJACI(2,1)*SF(3,K,J);
    DNDY(K)=RJACI(1,2)*SF(2,K,J)+RJACI(2,2)*SF(3,K,J);

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```

end

% -----
% Include user written coefficients
% RXJ, RYJ, BXJ, BYJ, GVJ, HVJ
% -----
temperature_COEF

% -----
% Create element stiffness matrix
% -----
DV=DETJ;
if IRZ == 1
    DV=2.0*PI*XJ*DV;
elseif IRZ == 2
    DV=2.0*PI*YJ*DV;
end

for K=1:NNPE;
    QE(K)=QE(K)+WT(1,J)*SF(1,K,J)*HVJ*DV;
    SFK=SF(1,K,J);
    for L=1:NNPE;
        SFL=SF(1,L,J);
        S(K,L)=S(K,L)+ ...
            WT(1,J)*(DNDX(K)*RXJ*DNDX(L)+DNDY(K)*RYJ*DNDY(L) ...
                -SFK*BXJ*DNDX(L)-SFK*BYJ*DNDY(L) ...
                -SFK*GVJ*SFL)*DV;
    end
end
end
% ----- end of volume quadrature

% -----
% Begin surface quadrature
% -----
for J=1:NSPE
    CHKH=1;
    CHKQ=1;
    for K=1:NNPS;
        J1=NP(I,NPSIDE(J,K));
        CHKH=CHKH*HS(J1);
        CHKQ=CHKQ*QS(J1);
    end

    if CHKH ~= 0 | CHKQ ~= 0
        KEND=NUMQPT(2);
        for K=1:KEND;
            YK = 0.0;
            XK = 0.0;
            dxdu = 0.0;
            dydu = 0.0;
            HSK = 0.0;
            QSK = 0.0;
            PHIK = 0.0;
            for L=1:NNPS;

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```

        L1=NPSIDE (J, L) ;
        NPL=NP (I, L1) ;
        XK    =XK    +SF (4, L, K)*XORD (NPL) ;
        YK    =YK    +SF (4, L, K)*YORD (NPL) ;
        dxdu  =dxdu  +SF (5, L, K)*XORD (NPL) ;
        dydu  =dydu  +SF (5, L, K)*YORD (NPL) ;
        QSK   =QSK   +SF (4, L, K)*QS (NPL) ;
        HSK   =HSK   +SF (4, L, K)*HS (NPL) ;
        PHIK  =PHIK  +SF (4, L, K)*PHIa (NPL) ;
    end
    dsdu = sqrt (dxdu ^2+dydu ^2) ;
    duds = 1/dsdu;

    DS=dsdu;
    if IRZ == 1
        DS=2.0*PI*XK*DS;
    elseif IRZ == 2
        DS=2.0*PI*YK*DS;
    end

    for L=1:NNPS;
        L1=NPSIDE (J, L) ;
        if CHKQ ~= 0
            QE (L1)=QE (L1)+WT (2, K)*SF (4, L, K)*QSK*DS;
        end
        if CHKH ~= 0
            QE (L1)=QE (L1)+WT (2, K)*SF (4, L, K)*HSK*PHIK*DS;
            for M=1:NNPS;
                M1=NPSIDE (J, M) ;
                S (L1, M1)=S (L1, M1)+ ...
                    WT (2, K)*SF (4, L, K)*HSK*SF (4, M, K)*DS;
            end
        end
    end

    end % of surface quadrature

    end % if-statement for quadrature

end % of loop over element sides

% -----
% Place completed element matrix in global SK and Q matrices
% -----
for J=1:NNPE
    JNP=NP (I, J) ;
    JEQ=NWLD (JNP) ;
    RHS (JEQ)=RHS (JEQ)+QE (J) ;
    for K=1:NNPE
        KNP=NP (I, K) ;
        KEQ=NWLD (KNP) ;
        KB= (KEQ-JEQ)+IDIAG;
        SK (JEQ, KB)=SK (JEQ, KB)+S (J, K) ;
    end
end

end % Loop over elements

```

```
% -----  
% Specify known values of PHI  
% -----  
for I=1:NUMNP;  
    if NPBC(I) == 1  
        NI=NWLD(I);  
        SK(NI,IDIAG)=SK(NI,IDIAG)*1.0E+06;  
        RHS(NI)=PHI(I)*SK(NI,IDIAG);  
    end  
end  
  
% -----  
% Call Gauss elimination routine  
% -----  
PHI = nGAUSS(SK,RHS,NUMNP,IB);  
  
% -----  
% Renumber solution values using original node numbers  
% -----  
for I=1:NUMNP;  
    NI=NWLD(I);  
    RHS(I)=PHI(NI);  
end  
for I=1:NUMNP  
    PHI(I)=RHS(I);  
end  
  
save PHI PHI -ASCII
```