$$V=\mathbb{R}^3 \text{ with basis } B_1=\left\{\begin{bmatrix}1\\0\\1\end{bmatrix},\begin{bmatrix}1\\1\\0\end{bmatrix},\begin{bmatrix}3\\1\\1\end{bmatrix}\right\}$$

$$W = \mathbb{R}^2$$
 with basis $B_2 = \left\{ \begin{bmatrix} 5 \\ 3 \end{bmatrix}, \begin{bmatrix} 4 \\ 6 \end{bmatrix} \right\}$

T is a linear transformation from V to W, and is given by:

$$T\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}_{S}\right) = \begin{bmatrix} x + y \\ z \end{bmatrix}_{S}$$

1) Using the information above, find a formula for T that allows us to compute $T(\vec{x})$ when \vec{x} is expressed in the natural basis of V. You do not need to simplify the formula.

2) Suppose a linear transformation T goes from \mathbb{R}^{12} to \mathbb{R}^4 , and it is known that $A\vec{x} = \vec{b}$ has no solutions when $\vec{b} = \begin{bmatrix} 1 & 2 & 3 & 5 \end{bmatrix}^T$. What is the determinant of $[T]^T[T]$?

(Here A is the matrix representing T)