

Name \_\_\_\_\_ Test 2, Fall 2017

**Non-calculator portion. Turn this portion in before you take out your technology.**

1) An equation  $A\vec{x} = \vec{b}$  has the solution given below, where  $s_1$  and  $s_2$  are free variables. Express the solution as a meaningful linear combination of vectors.

$$x_1 = -1 + 2s_1$$

$$x_2 = 3s_1 + 2s_2$$

$$x_3 = s_1 - s_2$$

(6 points)

2) Expand the set below to give a basis for  $\mathbb{R}^2$ .

$$\left\{ \begin{bmatrix} 1 \\ -3 \end{bmatrix} \right\}$$

(4 points)

3) A  $8 \times 5$  matrix has a null space of dimension 3. What is the rank of  $A$ ?

(6 points)

4) Suppose the matrix  $A$  has size  $11 \times 7$ . That is, 11 rows and 7 columns. It is known that the equation  $A\vec{x} = \vec{0}$  has multiple solutions, but that  $A\vec{x} = [1 \ 2 \ 3 \ 3 \ 1]^T$  has no solutions. Find the *smallest* possible dimension the null space of  $A$  could have.

(6 points)

5) Find the determinant of the matrix below.

$$\begin{bmatrix} -4 & 2 & -2 \\ 1 & 0 & 1 \\ 3 & -1 & 1 \end{bmatrix}$$

(10 points)

6) Find the matrix  $A$  so that the linear transformation below is given by  $T(\vec{x}) = A\vec{x}$ .

$$T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$$
$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \mapsto \begin{bmatrix} x_2 - 5x_3 \\ 7x_3 \end{bmatrix}$$

(6 points)

7) Let  $B$  be defined below. Find the change of basis matrix  $[I]_B^S$ .

$$B = \left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 4 \\ 4 \\ 6 \end{bmatrix}, \begin{bmatrix} 0 \\ 2 \\ 5 \end{bmatrix} \right\}$$

(4 points)

8) Answer the following as true or false. A statement is true if it is *always* true; false if it is *ever* false.

(2 points each)

T F a) Every matrix  $A$  has a determinant.

T F b) The range,  $T(V)$ , of a linear transformation  $T: V \rightarrow W$  is a vector space.

T F c) If a linear transformation  $T: V \rightarrow W$  is one-to-one, then it is onto.

T F d) If  $A\vec{x} = \vec{b}$  can be solved for every choice of  $\vec{b}$ , then the linear transformation given by  $T(\vec{x}) = A\vec{x}$  is onto.

T F e) Using matrices, we can write down a formula for the solution  $\vec{x}$  to  $A\vec{x} = \vec{b}$  no matter what  $\vec{b}$  is.

9) Let  $T$  be the linear transformation below. Prove that  $T$  is onto by either using some theorem/concept or by finding the input  $\vec{x}$  that maps to the output  $\vec{y} = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$ .

$$T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$$
$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \mapsto \begin{bmatrix} x_1 \\ 2x_2 \end{bmatrix}$$

(4 points)

10) Let  $A$  be an  $n \times n$  matrix. You know that the matrix equation  $A\vec{x} = \vec{0}$  has more than one solution. What else can you say?

(4 points per insightful statement; 1 point per obvious statement; every incorrect statement nullifies a correct statement. 12 points maximum)

**Technology portion: After you turn in the non-calculator portion, you may take out your technology and finish this portion. If you're using a phone or tablet, leave it flat on the desk.**

Use the matrix  $A$ , below, for the problems on this page.

$$A = \begin{bmatrix} 1 & 1 & 2 & -1 & 1 \\ 1 & 2 & 1 & 0 & 2 \\ -1 & -4 & 1 & -2 & 3 \\ 1 & -2 & 5 & -4 & -2 \end{bmatrix}$$

11) Find the null space of  $A$ .

(6 points)

12) Is  $\begin{bmatrix} 1 \\ 2 \\ 3 \\ -2 \end{bmatrix}$  in the vector space spanned by  $\left\{ \begin{bmatrix} 1 \\ 1 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ -4 \\ -2 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 1 \\ 5 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ -2 \\ -4 \end{bmatrix} \right\}$ ? Why or why not?

(6 points)

13) Find a subset of the vectors below that is a basis of  $\mathbb{R}^3$

$$\left\{ \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}, \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 11 \\ 10 \\ 7 \end{bmatrix}, \begin{bmatrix} 7 \\ 6 \\ 4 \end{bmatrix}, \begin{bmatrix} 3 \\ 2 \\ 2 \end{bmatrix} \right\}$$

(6 points)

14) Let  $B_1$  and  $B_2$  be defined below. Find the change of basis matrix  $[I]_{B_1}^{B_2}$ .

$$B_1 = \left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 4 \\ 4 \\ 6 \end{bmatrix}, \begin{bmatrix} 0 \\ 2 \\ 5 \end{bmatrix} \right\}, \quad B_2 = \left\{ \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix}, \begin{bmatrix} 4 \\ -3 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}$$

(8 points)



15) Define the linear transformation  $T: \mathbb{R}^4 \rightarrow \mathbb{R}^3$  via  $T(\vec{x}) = A\vec{x}$ . What is  $T([1 \ 2 \ 4 \ 2]^T)$ ?

$$A = \begin{bmatrix} 6 & 1 & 2 & 1 \\ 3 & 1 & 0 & 0 \\ 0 & 2 & 2 & 1 \end{bmatrix}$$

(6 points)

16) Define the linear transformation  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^5$  via  $T(\vec{x}) = A\vec{x}$  where  $A$  is defined below. Is  $T$  one-to-one? Why or why not?

$$\begin{bmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \\ 0 & 1 & 2 \\ 0 & 3 & 6 \\ 1 & 1 & 1 \end{bmatrix}$$

(6 points)